

Program of the Conference

8 – 10 october 2024 50, Svetlanskaya Street, Vladivostok

8 october 2024

9.00 - 10.00	Registration of conference participants				
10.00 - 10.15	Opening of the International Conference on Ocean Study 2024. Dolgikh Grigorii, academician of RAS				
10.15 - 10.45	Plenary report Konoplin Alexandr, director of Academician M. D. Ageev Institute of Marin Technology Problems Far Eastern Branch of RAS (IMTP FEB RAS)				
10.45 - 11.15	Plenary report Rodionov Alexandr, scientific director of the hydroacoustic communications and navigations laboratory of IMTP FEB RAS				
11.15 - 11.30	Video about the World Ocean exploration				
Break until 14-00					
	Section Deep Ocean Research, Oceanography and Marine Environment (Section Chairman Dr. Alexander Rodionov)				
	(Section Chairman Dr. Alexander Rodionov)				
14-00 - 14.15	Olga Trusenkova *, Elena Kustova <i>The summer reversal of the East Kamchatka Current from satellite altimetry data</i> (V.I. Il'ichev Pacific Oceanological Institute FEB RAS)				
14-00 - 14.15 14.15 - 14.30	Olga Trusenkova *, Elena Kustova <i>The summer reversal of the East Kamchatka Current from</i>				
	Olga Trusenkova *, Elena Kustova <i>The summer reversal of the East Kamchatka Current from satellite altimetry data</i> (V.I. Il'ichev Pacific Oceanological Institute FEB RAS) Zhanna Tskhay*, Viktor Filatov <i>Spatial and temporal variations in thermal conditions during the saury fishery in the NorthWest Pacific based on satellite data</i> (Sakhalin branch of				

pressure sensors (Concern CSRI Elektropribor, JSC ITMO University)

Dmitry Gryazin*, Olga Belova Metrological support of wave meters based on hydrodynamic

15.00 - 15.15

^{* -} speeker of the report

Coffee break

Section Complex Mathematical Problems of Ocean Monitoring and Modeling (Section Chairman Dr. Alexander Inzartsev)

16.00 - 16.15	Sergey Dyakov*, Marina Aleksanina, Anton Karnatskiy Calculation of Drift Velocities and Compression/Rarefaction Zones of the Sea Ice Cover on Satellite Images of the KMSS/Meteor-					
16.15 - 16.30	M Device (IACP FEB RAS) Sergey Dyakov*, Marina Aleksanina, Anastasia Ershova Calculation of Compositional Maps of Son Surface Temperature from J.P. Magguroments of U.S. Catallitas (IACR FER RAS. FEEL)					
16.30 - 16.45	of Sea Surface Temperature from IR Measurements of US Satellites (IACP FEB RAS, FEFU) Alexey Ermoshkin*, Nikolay Bogatov, Ivan Kapustin, Aleksandr Molkov A Physical Based Method for Retrieval Ocean Currents and Significant Wave Height Using Doppler Marine					
16.45 - 17.00	Radar (A.V. Gaponov-Grekhov Institute of Applied Physics of the RAS) Iman Valizadeh*, Jaime Lloret_Mauri Multi-hop Communication for Underwater Wireless Sensor Networks (Valencia Polytechnic University)					
	9 october 2024					
09.30 - 10.00	Registration of conference participants					
	Section Unmanned Marine Vehicles and Systems (Section Chairman PhD Alexander Konoplin)					
10.00 - 10.15	Valeriy Knyazhev Fuel Cells for AUV Power Supply (IMTP FEB RAS)					
10.15 - 10.30	Mikhail Belousov*, Dmitry Yukhimets, Anton Gubankov <i>Development of Information-Control System for Unmanned Underwater Vehicle by Means of ROS2 (IMPP FEB RAS, IACP FEB RAS, Sevastopol State University, Admiral G.I. Nevelskoy Maritime State University)</i>					
10.30 - 10.45	Antonina Shupikova*, Valeriy Bobkov, Alexander Inzartsev <i>A Method for Underwater</i> Pipeline Tracking from Stereo Images (IMTP FEB RAS, IACP FEB RAS)					
10.45 - 11.00	Valeriy Knyazhev*, Vladimir Loshchenkov Storage of Reagents for Fuel Cells in the AUV (IMTP FEB RAS)					
11.00 - 11.15	Nikita Krasavin*, Alexander Konoplin <i>The Underwater Manipulator Position Correction</i> Method for Performing Contact Operations (IMTP FEB RAS)					
11.15 - 11.30	Yurii Matvienko*, Sergey Pereselkov, Viktor Kuz'kin Experimental Results of Autonomous Underwater Vehicle 2D-Hologram by a Vector Receiver (IMTP FEB RAS, Voronezh State University, General Physics Institute)					
	Coffee break					
	Section Navigation and Motion Control (Section Chairman PhD Fedor Dubrovin)					
12.00 - 12.15	Fedor Dubrovin <i>On Determining the Spatial Orientation of a Marine Navigation Platform</i> Based on Spatial Orientation Measurements of a Pair of Non-Collinear Measurement Bases (IMTP FEB RAS)					
12.15 - 12.30	Sergey Fadyushin*, Alexander Lentarev, Elena Vereschaginan, Yana Pafnuteva, Alexander Tretyak, Sergey Pashin Conceptual Fundamentals of the Symbiotic Partnership in the Course of Controlling ManMachine Systems of the Navigator-Ship Type (FEFU)					
12.30 - 12.45	Dmitry Yukhimets <i>The AUV Control System for Trajectory Movement Taking into Account the Limitations of its Thruster System</i> (IACP FEB RAS)					
12.45 - 13.00	Igor Gornostaev*, Anton Gubankov Development of Method of Generating a Reference Movement Speed of a Group of UAVs (IACP FEB RAS, IMTP FEB RAS, Admiral G.I. Nevelskoy Maritime State University)					
13.00 - 13.15	Alexey Pavlov An approach to debugging control algorithms for an autonomous underwater vehicle during highprecision navigation to port using data from deepsea television cameras (Concern CSRI Elektropribor)					

Section Underwater Robotics and Systems

(Section Chairman PhD Eduard Mursalimov)

14.00 - 14.15	Vladimir Gerasimov*, Alexey Filozhenko, Anton Komlev Energy Supply Of The Hybrid UUV And Information Exchange With The Onshore Control Post During The Service Of Underwater				
14.15 - 14.30	Mining Complexes (IMTP FEB RAS) Vladimir Kostenko*, Nikolai Naidenko, Roman Vasilenko Approach to the Development of a Steering Thruster Mathematical Model for the Dynamic Positioning Mode of an AUV Equipped with Manipulator (IMTP FEB RAS) Grigorii Eliseenko Information Flows Management in Heterogeneous Communication Channels Between AUV and Operator (IMTP FEB RAS) Alexander Yurmanov*, Roman Vasilenko, Maxim Panchuk Algorithm of Underwater Objects Identification Considering Defects (IMTP FEB RAS)				
14.30 - 14.45					
14.45 - 15.00					
	Coffee break				
15.30 - 15.45	Sergey Kasatkin*, Nadezhda Zlobina Assessment of Own Noise of Uderwater Glider Equipped with Combined Receivers (IMTP FEB RAS)				
15.45 - 16.00	Artemii Mametev*, Alexander Pavin Color Image Segmentation Algorithm for Autonomous Underwater Vehicles (IMTP FEB RAS)				
16.00 - 16.15	Anna Bykanova*, Jurii Matvienko, Oleg Lvov Development of a Command AUV for Controlling a Group of Hybrid AUVs for Operational Noise Field Monitoring <i>Station</i> (IMTP FEB RAS)				
16.15 - 16.30	Maxim Ivanov*, Oleg Stepanov, Valerii Zolotarevich, Andreii Motorin <i>Recursive and Nonrecursive Passive Target Localization Algorithms with Bearing-Only Measurements</i> (ITMO				
16.30 - 16.45	University, Concern CSRI Elektropribor, JSC) Andrey Pugachev*, Alexey Borovik Universal Programming Language For AUV Missions (IMTP BED RAS)				
16.45 - 17.00	Iman Valizadeh*, Jaime Lloret_Mauri Localization Techniques in Underwater Wireless Sensor Networks (Valencia Polytechnic University)				
	10 october 2024				
13-30 - 14.00	Registration of conference participants				
	Section Underwater Robotics and Systems (Section Chairman PhD Alexander Pavin)				
14.00 - 14.15	Vladimir Kostenko <i>Calculation and Experimental Methodology for Assessing the Autonomy</i> Parameters of the AUV (IMTP FEB RAS)				
14.15 - 14.30	Vladislav Mikhailov*, Vladimir Gerasimov Development of a Cable Communication System for an Underwater Vehicle with a Bottom Station (IMTP FEB RAS)				
14.30 - 14.45	for an Underwater Vehicle with a Bottom Station (IMTP FEB RAS) Konstanin Shilin*, Alexander Pavin Light Neural Network for Pipeline Segmentation on a Side-Scan Sonar Images (IMTP FEB RAS, IACP FEB RAS)				
14.30 - 14.45 14.45 - 15.00	for an Underwater Vehicle with a Bottom Station (IMTP FEB RAS) Konstanin Shilin*, Alexander Pavin Light Neural Network for Pipeline Segmentation on a Side-Scan Sonar Images (IMTP FEB RAS, IACP FEB RAS) Alexander Protsenko*, Aleksey Kabanov, Alexander Zuev, Alexey Zhirabok The Optimal Astatic Observer for the Identification of Disturbances in Nonlinear Robotic Systems (IMTP				
	for an Underwater Vehicle with a Bottom Station (IMTP FEB RAS) Konstanin Shilin*, Alexander Pavin Light Neural Network for Pipeline Segmentation on a Side-Scan Sonar Images (IMTP FEB RAS, IACP FEB RAS) Alexander Protsenko*, Aleksey Kabanov, Alexander Zuev, Alexey Zhirabok The Optimal Astatic Observer for the Identification of Disturbances in Nonlinear Robotic Systems (IMTP FEB RAS, Sevastopol State University) Alexander Torzhkov*, Grigorii Eliseenko, Alexander Pavin Using Python to Create Control				
14.45 - 15.00	for an Underwater Vehicle with a Bottom Station (IMTP FEB RAS) Konstanin Shilin*, Alexander Pavin Light Neural Network for Pipeline Segmentation on a Side-Scan Sonar Images (IMTP FEB RAS, IACP FEB RAS) Alexander Protsenko*, Aleksey Kabanov, Alexander Zuev, Alexey Zhirabok The Optimal Astatic Observer for the Identification of Disturbances in Nonlinear Robotic Systems (IMTP FEB RAS, Sevastopol State University)				
14.45 - 15.00 15.00 - 15.15	for an Underwater Vehicle with a Bottom Station (IMTP FEB RAS) Konstanin Shilin*, Alexander Pavin Light Neural Network for Pipeline Segmentation on a Side-Scan Sonar Images (IMTP FEB RAS, IACP FEB RAS) Alexander Protsenko*, Aleksey Kabanov, Alexander Zuev, Alexey Zhirabok The Optimal Astatic Observer for the Identification of Disturbances in Nonlinear Robotic Systems (IMTP FEB RAS, Sevastopol State University) Alexander Torzhkov*, Grigorii Eliseenko, Alexander Pavin Using Python to Create Control Systems for Unmanned Underwater Vehicles (IMTP FEB RAS) Andrei Medvedev*, Vladimir Kostenko, Irina Mokeeva Modeling the Movement of a ROV Taking into Account the Influence of a Communication Cable (IMTP FEB RAS) Mikhail Panin*, Valery Bobkov, Mikhail Morozov, Alexander Inzartsev AUV Inspection of Subsea Pipelines Using Information from an Onboard Stereo Camera (IMTP FEB RAS, IACP				
14.45 - 15.00 15.00 - 15.15 15.15 - 15.30	for an Underwater Vehicle with a Bottom Station (IMTP FEB RAS) Konstanin Shilin*, Alexander Pavin Light Neural Network for Pipeline Segmentation on a Side-Scan Sonar Images (IMTP FEB RAS, IACP FEB RAS) Alexander Protsenko*, Aleksey Kabanov, Alexander Zuev, Alexey Zhirabok The Optimal Astatic Observer for the Identification of Disturbances in Nonlinear Robotic Systems (IMTP FEB RAS, Sevastopol State University) Alexander Torzhkov*, Grigorii Eliseenko, Alexander Pavin Using Python to Create Control Systems for Unmanned Underwater Vehicles (IMTP FEB RAS) Andrei Medvedev*, Vladimir Kostenko, Irina Mokeeva Modeling the Movement of a ROV Taking into Account the Influence of a Communication Cable (IMTP FEB RAS) Mikhail Panin*, Valery Bobkov, Mikhail Morozov, Alexander Inzartsev AUV Inspection of				